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#### Freeform Optics Incubator 30 OCTOBER - 1 NOVEMBER 2011

#### OSA Headquarters • Washington, D.C., USA

Hosted by: Pablo Benitez, Universidad Politecnica de Madrid, Spain and Kevin Thompson, Synopsys, Inc., USA

### Highlights of Presentations Part 2 of 3 Day 1, Afternoon compiled by Kevin Thompson, PhD Synopsys, Inc.



Seven Thompson, Synopsys, Inc., USA         9:00       Freeform Surfaces for Imaging Systems Norbert Kerwien, Carl Zeiss Corp., Germany         9:25       Current Techniques for Diamond Machining Freeform Optics Gregg Davis, II-VI, Inc., USA         9:50       Realizing an Optical System with Phi-Polynomial Freeform Surfaces Kyle Fuerschbach, University of Rochester, USA
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11:00 Specifying ShapeWhat Could We Hope For and Can It Be Achieved
Gregory Forbes, QED Technologies Inc., Australia
11:25 Smooth Radial Basis Functions Viewed as a Generalization of Multivariate Polynomials
Gregory Fasshauer, Illinois Institute of Technology, USA
11:50 Moving from Phi-Polynomial to Multi-centric Radial Basis Functions
Aaron Bauer, University of Rochester, USA
13:15 SMS 3D: A Freeform Optics Design Method
Juan-Carlos Miñano, LPI, Universidad Politecnica de Madrid, Spain
13:40 Geometric Methods of Design of Freeform Surfaces with Prescribed Optical Properties
Vladimir Oliker, Emory University, USA
14:05 A Starting Point Approach for Nonimaging Reflector Design
Cristina Canavesi, University of Rochester, USA
15:10 40 years of Freeform Surfaces
Daniel Bajuk, ZYGO EPO, USA
15:35 Freeform Surfaces Have Aberration Fields Too
Kevin Thompson, Synopsys, Inc., USA
16:00 Two Freeform Mirror Designs with SMS 3D
Lin Wang, Universidad Politecnica de Madrid, Spain
17:30 BIG BIRD
Phil Pressel, Quartus Engineering Company, USA
9:00 The Art of Tailoring Freeform Surfaces for Illumination
William Cassarly, Synopsys, Inc., USA
9:25 Freeform Optics at OSRAM: What We Have, What We Miss, What We Need
Julius Muschaweck, OSRAM GmbH, Germany
9:50 Freeform Optics for a Linear Field of View
Fabian Duerr, Vrije Universiteit Brussel, Belgium
11:00 Nonimaging Freeform Optics Applications at LPI
Pablo Benitez, Universidad Politecnica de Madrid, Spain
11:25 F-RXI Photovoltaic Concentrator: A High Performance SMS-3D Freeform Köhler Design
Marina Bulian. Universidad Politecnica de Madrid. Spain
11:35 Augmented Reality Displays a Playground for Freeform Surfaces
Jannick Rolland, University of Rochester. USA



#### Day 1 Afternoon Session

Illumination Optics; an Introduction Bill Cassarly, Synopsys, Inc., USA

- 13:15 SMS 3D: A Freeform Optics Design Method Juan-Carlos Miñano, LPI, Universidad Politecnica de Madrid, Spain
- 13:40 Geometric Methods of Design of Freeform Surfaces with Prescribed Optical Properties Vladimir Oliker, *Emory University, USA*
- 14:05 A Starting Point Approach for Nonimaging Reflector Design Cristina Canavesi, University of Rochester, USA
- 15:10 **40 years of Freeform Surfaces** Daniel Bajuk, *ZYGO EPO, USA*
- 15:35 Freeform Surfaces Have Aberration Fields Too Kevin Thompson, Synopsys, Inc., USA
- 16:00 **Two Freeform Mirror Designs with SMS 3D** Lin Wang, *Universidad Politecnica de Madrid, Spain*



### Surfaces for Illumination Part 1 - Introduction

#### **Freeform Incubator**

Dr. Bill Cassarly Optical Research Associates williamc@synopsys.com www.opticalres.com

### **Illumination Optics**

 Includes applications in virtually every industry where light must be controlled. Almost all applications now use LEDs.



### **Reflector Applications**

- Luminaires
- Flashlights
- Street lighting
- Medical illuminators
- Automotive headlights
- Projection displays
- Laser beam shaping





### **Diffusers and scatter**

 Many illumination products combine an optic that collects light and also spread/homogenizes the beam pattern.

- Lens arrays, faceted reflectors, diffusers





### Optimization

- Optimization is the ability to automatically refine the performance of a system based upon a user specified performance criteria
- Three primary aspects of optimization
  - Efficient Optimization Algorithm
  - Smart Model Parameterization
  - Robust Merit Function





### **Surface Parameterization**





NURBS curve and NURBS surface







- Surfaces can be described using Equation:
  - e.g., XYPolynomial, Zernike, Asphere, etc
- Tailoring and SMS:
  - Compute prescribed surface(s) by numerical integration.
    - Often based upon a source to output mapping
    - Surface commonly represented using NURBS
- Equation that best fits NURBS sometimes used

### **Optimization Variables**



- Equation Parameters
  - e.g., radius of curvature, XY polynomial coefficients
- Source to Output Mapping parameters

   e.g., Width of target, desired Illuminance



### **Merit Function**

- For many applications, a weighted Merit Function can be used for optimization.
- Weights are used by the designer to help balance tradeoffs.
- Merit functions are often based on ray aiming.
- In illumination, binned Monte Carlo simulation results are often used.



#### **Basic Equation For Merit Function**

- $MF = \sum W_g \sum W_i^2 (V_i T_i)^2$ 
  - $W_g =$  Weight of  $g^{th}$  MF Group
  - $W_i$  = Weight of i<sup>th</sup> MF item in Group g
  - $V_i$  = Current Value of i<sup>th</sup> MF item
  - $T_i$  = Target of i<sup>th</sup> MF item



# Computer Speed makes Monte Carlo Optimization feasible



Adapted from K. Thompson, "Optical Design, Information and Insights," Invited, Presented to the Committee on Optical Science and Engineering, National Academy of Sciences (1996)

### SMS 3D: A Freeform Optics Design Method

J.C.Miñano<sup>1,2</sup>, Pablo Benítez<sup>1,2</sup>

#### <sup>1</sup>Universidad Politécnica de Madrid, Spain <sup>2</sup>LPI, USA





### Design methods in nonimaging optics

- 1. String method (1960's)
- 2. Flow line method (1970's)
- 3. Taylored Edge-ray method (1980's)
- 4. Poisson bracket method (1980's)
- 5. Lorentz geometry method (1990's)
- 6. Point-source Differential Equation methods (1960's)
- 7. Numerical optimization methods (1990's)
- 8. Simultaneous Multiple Surface (SMS) method (1990's)
- 2D = rotational or linear symmetry 3D = freeform



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Only 2D

2D and 3D

#### SMS design method







### **RXI** collimator



Free form RXI











### Conclusions

- SMS 3D is a free-form optical design method. As yet up to 2 surfaces/device have been designed. Following the same scheme as in SMS 2D, four or more free-form surfaces may be handled with this method
- As a nonimaging design tool:
  - it allows control of the size and rotation of the pinhole images of the source, which is critical for extended sources.
  - Efficiency tolerance improvement.
  - Reflector combinations avoiding blockage
  - Compact designs
- As an imaging design tool:
  - Field contours can be better adapted to rectangles: Less optical surfaces
  - reflector combinations avoiding blockage
  - Compact designs





#### Geometric methods for design of freeform surfaces

Vladimir Oliker Emory University, Atlanta oliker@mathcs.emory.edu

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V. Oliker/Emory

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Two basic approaches to design of freeform optics (See J. C. Miñano, P. Benítez, A. Santamaría, Opt. Review, 2009):

- Numerical Optimization of some Merit function(s). Numerous procedures exist; The design is usually a local optimum of the merit function
- **Direct methods;** require a correspondence (map) between prescribed input and output fronts
  - (a) Spherical wave fronts were considered already by R. Descartes;
  - (b) The SMS method, J. C. Miñano, P. Benítez et al.;
  - (c) Geometric methods (
     =The Monge-Ampère equations), V.I. Oliker et al.

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Freeform Optics

#### Philosophy of applying geometric methods to design of freeform mirrors/lenses:

- Recognize special surfaces (i.e. quadric(s), Cartesian ovals,...) suitable for the problem (These usually solve the problem if one of the given intensities replaced by a sum of Dirac masses)
- 2. Describe the freeform mirrors/lenses as expressions for lower and upper envelopes of such special surfaces (This also defines convex/nonconvex solutions, the admissible functions and often a very useful Fermat-like functional!)

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Freeform Optics

#### Philosophy of applying geometry to design of freeform mirror/lenses (cont-d):

- 3. (a) An iterative method based on a monotone variation of parameters defining special surfaces has been developed by V. Oliker et al.; This method is very general and intuitive and the procedure is guaranteed to converge to the true solution (a priori chosen by the user; may become slow when the number of special surfaces is large
- 3. (b) A new method was developed by V. Oliker et al. in recent years. It is based on specific rules for formulating a problem-dependent physically motivated Fermat-like functional to be optimized; the numerical scheme is guaranteed to converge to the true solution (a priori chosen by the user); it allows determination of tens of thousands of data points on each mirror/lens.

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**Test design 1. A freeform mirror.** The mirror below transforms an intensity from a point source into a prescribed far-field distribution; the mirror was designed by V. Oliker; data for the design was supplied by J. C. Miñano, P. Benítez;



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Freeform Optics

#### Our main claims are:

- Freeform lenses can be designed under very general assumptions.
- Analytically, these problems can be formulated as:
   (a) PDE's of Monge-Ampère type, (b) Variational problems
- Two designs are available for the same data; one of them always consists of a concave and convex lenses.
- Practical computational approaches are developed for calculating solutions with  $\approx$  40,000 surface data points on each lens.

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# A starting point approach for non-imaging reflector design

#### Cristina Canavesi,<sup>1</sup> William J. Cassarly, PhD,<sup>2</sup> and Prof. Jannick P. Rolland<sup>1</sup>

<sup>1</sup>The Institute of Optics, University of Rochester

<sup>2</sup>Synopsys

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## Some Reflector Design Methods

#### Numerical integration

• Set up system of equations and solve numerically





- H. Ries & J. Muschaweck, Tailored freeform optical surfaces, J. Opt. Soc. Am. A 19(3), 590-595, (2003)
- H. Ries, J. Muschaweck, & A. Timinger, "New methods of reflector design", OPN , 46-49 (2001)

#### Variable separation mapping

У

• Subdivide problem in equi-flux regions and assign mapping. For unfaceted reflectors, can result in issues at the boundary.





W. A. Parkyn, "Illumination lenses designed by extrinsic differential geometry", SPIE 3482, 389-396 (1998).
L. Wang, K. Qian and Y. Luo, "Discontinuous free-form lens design for prescribed irradiance", Appl. Opt. 46(18) 3716-3723 (2007).



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### **Some Reflector Design Methods**

#### **Oliker supporting ellipsoids algorithm**

• Initially flux is all collected by one ellipsoid, then the ellipsoids are scaled iteratively to all receive rays

- systems," Opt. Lett. 36, 918-920 (2011) Linear programming (Oliker/Wang)
- Variational formulation



• T. Glimm and V. Oliker, "Optical design of single reflector systems and the Monge-Kantorovich mass transfer problem", J. of Mathematical Sciences, 117(3), 4096-4108 (2003)

• V. I. Oliker, "Mathematical aspects of design of beam shaping surfaces in geometrical optics," Trends in

• D. Michaelis, P. Schreiber, and A. Bräuer, "Cartesian oval representation of freeform optics in illumination

"Designing freeform reflectors for extended sources",

Nonlinear Analysis, pp. 191–222 (2002)

Proc. SPIE 7423, 742302 (2009)

• F. R. Fournier, W. J. Cassarly and J. P. Rolland,

- Xu-Jia Wang, "On the design of a reflector antenna II," Calc. Var. 20, 329–341 (2004)
- V. Oliker, "Geometric and variational methods in optical design of reflecting surfaces with prescribed irradiance properties", Proc. SPIE 5942, 594207 (2005)





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OPTICS



ROCHESTER

Predictable Success

### **3D Example and Comparison with Supporting Ellipsoids Starting Point**







### Conclusion

- The linear program finds a solution in which the rays represent intersections between paraboloids
- Running the linear programming method with a small or big number of rays per reflector yields the same focal parameters
- With a low number of rays per reflector, the linear programming starting point is better than the ellipsoids starting point (lower rms, lower peak-to-valley)





zygo

Strengthen | Expand | Grow

#### 40+ Years of Freeform Surfaces

Dan Bajuk (dbajuk@zygo.com) Bob Kestner (bkestner@zygo.com)

#### ZYGO

Extreme Precision Optics Richmond, CA

November 1, 2011



### **Freeform Surface Definition**

- "Freeform Optical surfaces are defined as any nonrotationally symmetric surface or a symmetric surface that is rotated about any axis that is not its axis of symmetry."
  - Design tools for freeform optics Authors: K. Garrard; T.Bruegge; J. Hoffman; T. Dow; A. Sohn
- Surface examples
  - Bi-cubic spline
  - Bi-variant polynomial
  - Aspheric cylinder
  - Toroid
  - Phase correctors
  - Zernike surfaces
  - Off-axis asphere
    - fabricated via freeform methods



6-fold symmetry phase corrector Courtesy of B. Catanzaro



### **TV Phosphor Exposure Lenses**



Typical TV lens profile – aspheric departure about 4mm



- TV lenses <u>freeform aspheres</u> were used to lithographically place phosphors on a color CRT tube face in the position where the electron beam (R,G,B) would land during use.
- Lenses were generally produced in small lots (6 to 12) for each color tube design
- TV lenses were manufactured at rates up to 40/week between 1967 and 2003



Hartmann test used to verify surface profile



#### **Alvarez Lens Mold**



- Manufactured for an automated vision analyzer
  - Cubic form of Alvarez lens produces variable power by translating two lenses rotated by 180°

Translation of rotated lens pair produces variable power







#### **Hubble Space Telescope Optics**



Deep Field ACS image

#### **EUV Mirrors**



	Figure	MSFR*	HSFR*
Specification	<0.10nm rms	0.14nm rms	0.15nm rms
Results range	0.087-0.051	0.121-0.089	0.079-0.055

- Zygo EPO has been supplying EUV optics to the semiconductor community since 1992
- Continued process improvement has resulted in 0.1nm rms results over a broad spatial spectrum from full aperture to 10nm





### **Lithographic Freeform Fold Mirror**



### zygo

### Summary

- Freeform surfaces have been manufactured for over 40 years using computer controlled fabrication methods
  - Today's processes can achieve nanometer precision
- Flexible and precise figure metrology methods are key
  - CGH interferometry
  - Stitching interferometry
  - Coordinate measuring machines
  - Metrology covering a broad spatial frequency range is required for the most demanding application
  - PSD evaluation





### Freeform Surfaces have Field Dependence Too





Kevin P. Thompson, PhD

Group Director, R&D/Optics, Synopsys, Inc. Visiting Scientist, Institute of Optics, UofR

#### October, 2011



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### **Two flavors of Freeform surfaces**

- Freeform Surfaces for Optical Design
  - Comatic and/or Phi-Polynomial (Zernikes)



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#### - Multi-centric Radial Basis Functions



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# These are THE Aberrations (there are not any others)



Predictable Success

### This is Important (generalizing for no symmetry)

A fundamental **assumption** has been that the "Y-axis" is aligned to the field point of interest – this has been a long standing impediment



Predictable Success

# Freeform surfaces reveal the true nature of astigmatism



Schmid, T., J.P. Rolland, A. Rakish, and K.P. Thompson, "Separation of the effects of astigmatic figure error and misalignments using NAT", Optics Express 18(16), 17433-17447 (2010)





Conclusions: Impact of "Freeform Surfaces" on Optical Design

- The addition of comatic surfaces to the suite is a dramatic advance for optical design
- The new design space is virtually unexplored and for unobscured mirror systems and intrinsically nonsymmetric designs (e.g. Head Worn Displays) the new opportunities are substantial
- Testing is the dominant impediment at this time



### Two Freeform Mirror Designs with SMS 3D

Wang Lin, Pablo Benítez, J.C.Miñano, Guillermo Biot

Universidad Politecnica de Madrid



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0.22. (shifting white)

#### **Design description**





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12. Lan Jina an Inde

#### One of two examples presented for configuration 1

#### 1<sup>st</sup> configuration

++ RMS\_Avg = 6um

Distortion < 0.2%





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#### Summary

- Optimization with SMS 3D method
- Exploration of 4 families of 2 configurations



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